

In the specification:

Page 12, first paragraph, amend as follows:

A rotatably driven sensing unit 56 is arranged between the curved tracks 46, 48. The sensing unit 56 is formed as a ring-shaped component. It has five radially outwardly extending web-like sensing members 68 and two radially inwardly extending drive elements 110 shown in Figure 4, which are uniformly distributed over the periphery. The sensing unit 56 is in operative connection with the sensing member [66] 68 during an impact operation with the curved tracks 46, 48. In order to reduce the wear between the sensing means 68 and the curved tracks [26] 46, 48, the sensing members 68 are chamfered to their side surfaces.

Page 12, second paragraph, amend as follows:

The [component which forms the] 56 sensing unit is arranged axially displaceably on the striker 32 between two helical pressure springs 112, 114 (Figure 3). The helical pressure spring 112 which faces the tool receptacle [20] 30 is supported in direction of the tool receptacle 30 on a projection 116 formed on the striker [42] 32 and acts in the direction opposite

to the tool receptacle 30 on the sensing unit 56. The helical pressure spring 114 which faces away from the tool receptacle 30 is supported in a direction which is opposite to the tool receptacle 30 through a spring abutment 170 and through a safety ring 118 mounted on the striker 32 against the striker 32. It acts in direction of the tool receptacle 30 on the sensing unit 56.

Amended specification:

Page 12, first paragraph, amended:

β ²
A rotatably driven sensing unit 56 is arranged between the curved tracks 46, 48. The sensing unit 56 is formed as a ring-shaped component. It has five radially outwardly extending web-like sensing members 68 and two radially inwardly extending drive elements 110 shown in Figure 4, which are uniformly distributed over the periphery. The sensing unit 56 is in operative connection with the sensing member 68 during an impact operation with the curved tracks 46, 48. In order to reduce the wear between the sensing means 68 and the curved tracks 46, 48, the sensing members 68 are chamfered to their side surfaces.

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The 56 sensing unit is arranged axially displaceably on the striker 32 between two helical pressure springs 112, 114 (Figure 3). The helical pressure spring 112 which faces the tool receptacle 30 is supported in direction of the tool receptacle 30 on a projection 116 formed on the striker 32 and acts in the direction opposite to the tool receptacle 30 on the sensing

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B unit 56. The helical pressure spring 114 which faces away from the tool receptacle 30 is supported in a direction which is opposite to the tool receptacle 30 through a spring abutment 170 and through a safety ring 118 mounted on the striker 32 against the striker 32. It acts in direction of the tool receptacle 30 on the sensing unit 56.
